

**THE IMAGINATION UNIVERSITY PROGRAMME**

**RVfpga-SoC**

**Installation Guide**

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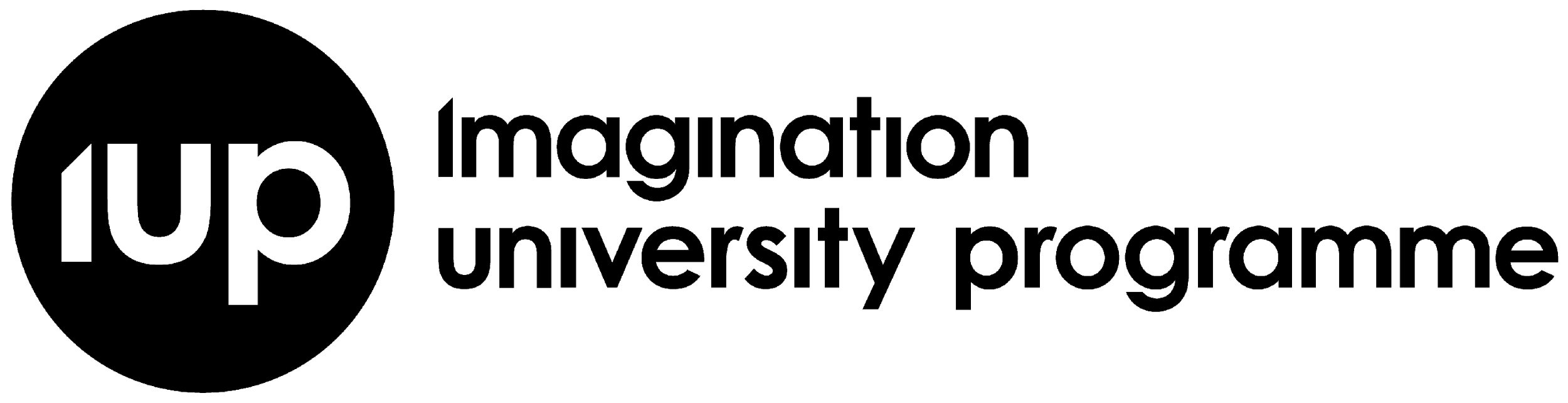
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# INTRODUCTION

This guide shows how to install tools and hardware needed for RVfpga-SoC on the Ubuntu 18.04 operating system (OS). **The instructions below are for an Ubuntu 18.04 OS**, but other Linux operating systems and Windows follow similar (if not exactly the same) steps. We insert boxes with specific instructions for the Windows OS in some cases. If you are using Ubuntu, ignore those boxes.

This process can take several hours (or more, depending on your download speed), but most of the time is spent waiting while the programs are downloaded and installed.

Table 1 lists the software and hardware needed for RVfpga-SoC.

**Table 1. Required Software and Hardware for RVfpga-SoC**

|  |  |  |
| --- | --- | --- |
| **Software** | | |
| **Name** | **Website** | **Cost** |
| Vivado 2019.2 WebPACK | <https://www.xilinx.com/support/download/index.html/content/xilinx/en/downloadNav/vivado-design-tools/2019-2.html> | free |
| VSCode | <https://code.visualstudio.com/Download> | free |
| PlatformIO | <https://platformio.org/>  Installed within VSCode | free |
| Verilator (an HDL simulator) and GTKWave | <https://github.com/verilator/verilator>  <http://gtkwave.sourceforge.net/> | free |
| FuseSoC | <https://github.com/olofk/fusesoc> | free |
| RISC-V Toolchain and OpenOCD | <https://github.com/riscv/riscv-gnu-toolchain>  <https://github.com/riscv/riscv-openocd>  Installed within PlatformIO | free |
| Zephyr Project | <https://github.com/zephyrproject-rtos/zephyr> | free |
| **Hardware\*** | | |
| **Name** | **Website** | **Cost** |
| Nexys A7 FPGA Board\* | <https://store.digilentinc.com/nexys-a7-fpga-trainer-board-recommended-for-ece-curriculum/> | $265  (academic price: $199) |
| **RISC-V Core and System-on-Chip (SoC)\*\*** | | |
| **Name** | **Website** | **Cost** |
| Western Digital’s  SweRV EH1 Core | <https://github.com/chipsalliance/Cores-SweRV> | free |
| SweRVolf | <https://github.com/chipsalliance/Cores-SweRVolf> | free |

\* Hardware is optional.

\*\* The SweRV EH1 core and SweRVolf are provided as part of the RVfpga-SoC package.

# Installation for Lab 1

Vivado is a Xilinx tool for viewing, modifying, and synthesizing Verilog code. You will use it extensively in later labs. The installation instructions are available at <https://reference.digilentinc.com/vivado/installing-vivado/start> and are summarized below.

**Windows:** the webpage referenced above (<https://reference.digilentinc.com/vivado/installing-vivado/start>) also includes detailed instructions for installing Vivado in Windows. Below we insert boxes when specific instructions are required for Windows.

1. **Install Vivado:**

**Step** **1**. Navigate to <https://reference.digilentinc.com/vivado/installing-vivado/start>

**Step 2**. You will be guided to the Xilinx download page: <https://www.xilinx.com/support/download.html>

**Step 3**. It is recommended that you install the “Self Extracting Web Installer”. At the time of writing this document, it is at this link on the download page: [Xilinx Unified Installer 2019.2: Linux Self Extracting Web Installer](https://www.xilinx.com/member/forms/download/xef.html?filename=Xilinx_Unified_2019.2_1106_2127_Lin64.bin)

**WINDOWS:** At the time of writing this document, the “Self Extracting Web Installer” for Windows is at this link on the download page: [Xilinx Unified Installer 2019.2: Windows Self Extracting Web Installer](https://www.xilinx.com/member/forms/download/xef.html?filename=Xilinx_Unified_2019.2_1106_2127_Win64.exe)

**Step 4**. You will be asked to log in to your Xilinx account before you can download the installer. If you don’t already have an account, you will need to create one.

**Step 5**. Execute the binary file. Open a terminal and make it root (type “sudo su”). Then drag the binary file (Xilinx\_Unified\_2019.2\_1106\_2127\_Lin64.bin) into the terminal. If it prompts you to make the file executable and run it, select OK.

* **Troubleshooting:** If the terminal says permission denied, type the following in the terminal (in the same directory as the binary file):

> sudo chmod +x ./Xilinx\_Unified\_2019.2\_1106\_2127\_Lin64.bin

> sudo ./Xilinx\_Unified\_2019.2\_1106\_2127\_Lin64.bin

**WINDOWS:** In Windows, you can simply execute the .exe file that you downloaded in steps 3 and 4 by double-clicking on it.

**Step 6**. The Vivado installer will walk you through the installation process. Important notes:

* Select **Vivado** (*not* Vitis) as the Product to install.
* Select Vivado HL **Webpack** (*not* Vivado HL System Edition); Webpack is free.
* Otherwise, defaults should be selected.

**Hint:** If you change the installation directory of Vivado, you would need to modify the path appropriately in the following steps.

**WINDOWS:** Steps 7 and 8 are not necessary for Windows. You can simply ignore these two steps and go directly to step 9.

**Step 7**. After Vivado has installed, you need to set up the environment. Open a terminal and type:

source /tools/Xilinx/Vivado2019.2/settings64.sh

Add that line (source /tools/Xilinx/Vivado2019.2/settings64.sh) to your ~/.bashrc file so that it runs each time you launch a terminal.

**Step 8**. Test Vivado by typing the following in a terminal:

vivado

**Troubleshooting:**

* If your system cannot find that executable, you’ll need to add the following to your path:

/tools/Xilinx/DocNav

/tools/Xilinx/Vivado/2019.2/bin

* If you get an error such as “application-specific initalization failed…”, type the following at a terminal:

sudo ln -s /lib/x86\_64-linux-gnu/libtinfo.so.6 /lib/x86\_64-linux-gnu/libtinfo.so.5

1. **Install Cable drivers:**

**Step 9**. You will need to **manually install the Nexys A7 FPGA board’s cable drivers**. Type the following at a terminal window:

cd /tools/Xilinx/Vivado/2019.2/data/xicom/cable\_drivers/lin64/install\_script/install\_drivers/

sudo ./install\_drivers

**WINDOWS:** Vivadoinstallation in Windows automatically installs drivers for the Nexys A7 board, which are not compatible with PlatformIO. Thus, if you are using Windows, **you must update the drivers as explained in Appendix A of the Installation Guide.**

1. **Install Digilent Board Files:**

**Step 10**. You will also need to manually install the Digilent Board Files.

* Download the [archive](https://github.com/Digilent/vivado-boards/archive/master.zip?_ga=2.158467251.828100773.1587959567-2022567073.1577108610) of the vivado-boards from the Github repository and extract it.
* Open the folder extracted from the archive and navigate to its *new/board\_files* directory. Select all folders within this directory and copy them.
* Open the folder that Vivado was installed into (*/tools/Xilinx/Vivado* by default). Under this folder, navigate to its *<version>/data/boards/board\_files* directory, then paste the board files into this directory.
* You can also use the terminal, by going into the *new/board\_files* directory and typing:

sudo cp -r \* /tools/Xilinx/Vivado/2019.2/data/boards/board\_files

**WINDOWS:** copy/paste the downloaded folders as explained in Step 10. In Windows, you can find Vivado’s *board\_files* folder at: *C:\Xilinx\Vivado\2019.2\data\boards\board\_files*

# Installation for Lab 2

Now you will install Visual Studio Code (VSCode), PlatformIO, Verilator, and GTKWave.

PlatformIO is an integrated development environment (IDE) for embedded systems that is built on top of Microsoft’s Visual Studio (VS) Code. It allows you to program the RISC-V processor (that is located on the FPGA) using C or assembly. PlatformIO is cross-platform and includes a built-in debugger.

Follow these steps to install both VSCode and PlatformIO:

1. **Install VSCode:**

Follow these steps to install VSCode:

* 1. Download the .deb file from the following link: <https://code.visualstudio.com/Download>
  2. Open a terminal, and install and execute VSCode by typing the following in the terminal:

cd ~/Downloads

sudo dpkg -i code\*.deb

code

**Windows:** VSCode packages are also available for Windows (.exe file) at <https://code.visualstudio.com/Download>. Follow the common steps used for installing and executing an application in these operating systems.

1. **Install PlatformIO on top of VSCode:**

Follow these steps to install PlatformIO:

* 1. Install python3 utilities by typing the following in a terminal:

sudo apt install -y python3-distutils python3-venv

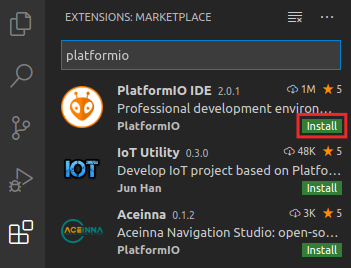
**Windows :** this step(2.a) is not required in Windows.

* 1. If not yet open, start VSCode by selecting the Start button and typing “VSCode” in the search menu, then select VSCode, or by typing code in a terminal.
  2. In VSCode, click on the Extensions icon  located on the left sidebar of VSCode (see Figure 1).



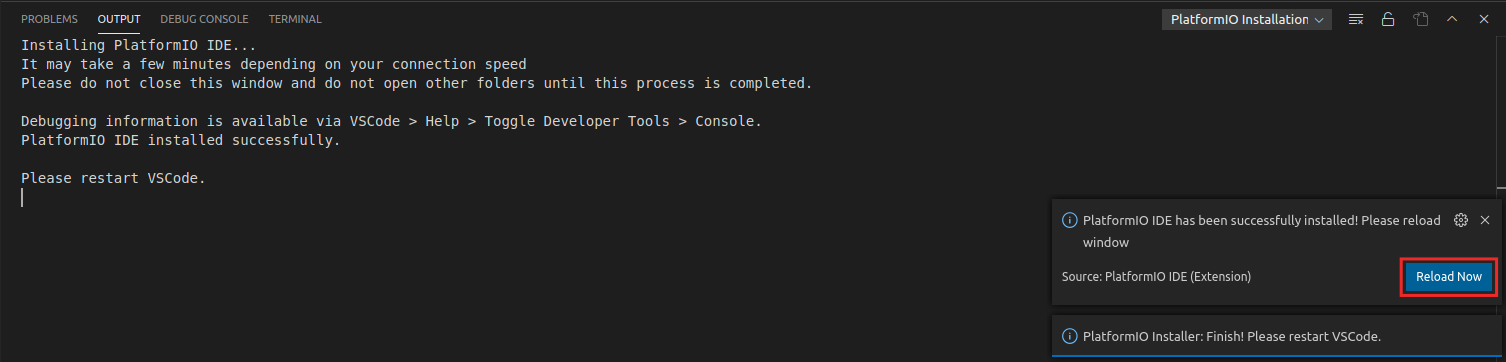
**Figure 1. VSCode’s Extensions icon**

* 1. Type *PlatformIO* in the search box and install the PlatformIO *IDE* by clicking on the install button next to it (see Figure 2).



**Figure 2. PlatformIO IDE Extension**

* 1. The OUTPUT window on the bottom will inform you about the installation process. Once finished, click “Reload Now” on the bottom right side window, and PlatformIO will be installed inside VSCode (see Figure 3).



**Figure 3. Reload Now after PlatformIO installs**

1. **Install GTKWave:**

Follow the next steps to install GTKWave in your Ubuntu 18.04 Linux system.

Open your ubuntu terminal and enter the following commands :

* sudo apt-get install git make autoconf g++ flex bison libfl2 libfl-dev
* sudo apt-get install -y gtkwave

**Windows :** See Appendix B for the Installation of GTKWave for Windows.

1. **Install Verilator:**

Follow the next steps to install Verilator (instructions are available at <https://www.veripool.org/projects/verilator/wiki/Installing> but are also summarized below)

* git clone https://git.veripool.org/git/verilator
* cd verilator
* git pull
* git checkout v4.106
* autoconf
* ./configure
* make (alternatively, you can use make -j$(nproc) to make it go faster)
* sudo make install
* export PATH=$PATH:/usr/local/bin (change the path in your system)

To add */usr/local/bin* permanently to your path, add the last line to your ~/.bashrc file.

**Windows :** See Appendix B for the Installation of Verilator for Windows.

# Installation for Lab 3

The Installation instructions from Lab 3 onwards are specifically for Ubuntu 18.04 operating system. The instructions will work the same for any other latest version of Ubuntu. It is highly recommended that you perform all these following labs on the Ubuntu operating system.

Follow the next steps to install the required software needed to complete Lab 3 :

1. **Install pip:**

“**pip**” is required for “FuseSoC” and “west” Installation. Open the Ubuntu terminal and enter the following command :

* sudo apt install python3-pip

1. **Install pyelftools:**

pyelftools is required for west build. We can Install pyelftools using 2 ways:

* pip3 install pyelftools

or

* sudo apt-get install -y python3-pyelftools python-pyelftools

1. **Install FuseSoC:**

To install the current stable version of FuseSoC, open a terminal window and run the following command. If an older version of FuseSoC is found on your system, this will upgrade the version to the latest stable release.

* sudo pip3 install --upgrade fusesoc

1. **Install OpenOCD:**

OpenOCD is an open on-chip debugger that allows users to program and debug embedded target devices. Follow the next steps to install RISC-V OpenOCD onto your computer:

* sudo apt-get install libusb-1.\*
* sudo apt-get install pkg-config
* git clone https://github.com/riscv/riscv-openocd.git
* cd riscv-openocd
* ./bootstrap

If you get an error of command not found then try executing :

sudo apt-get install libtool

* sudo apt-get install libusb-1.0-0-dev
* ./configure --enable-jtag\_vpi --enable-ftdi
* make
* sudo make install

# Installation for Lab 4

Follow the next steps to install the required software needed to complete Lab 4:

Open your Ubuntu terminal and enter the following commands :

1. **Prerequisites and Dependencies:**

* sudo apt update
* sudo apt upgrade
* sudo apt install --no-install-recommends git cmake ninja-build gperf \
* ccache dfu-util device-tree-compiler wget \
* python3-dev python3-pip python3-setuptools python3-tk python3-wheel xz-utils file \
* make gcc gcc-multilib g++-multilib libsdl2-dev

1. **Update \*cmake\* version to 3.13.1 or higher:**

* wget -O - https://apt.kitware.com/keys/kitware-archive-latest.asc 2>/dev/null |
* sudo apt-key add -
* sudo apt-add-repository 'deb https://apt.kitware.com/ubuntu/ bionic main'
* sudo apt update
* sudo apt install cmake

1. **Install west:**

* pip3 install --user -U west
* echo 'export PATH=~/.local/bin:"$PATH"' >> ~/.bashrc
* source ~/.bashrc

1. **Install Zephyr SDK :**

Install the Zephyr SDK v0.12.2

Run the following commands in your **home** directory.

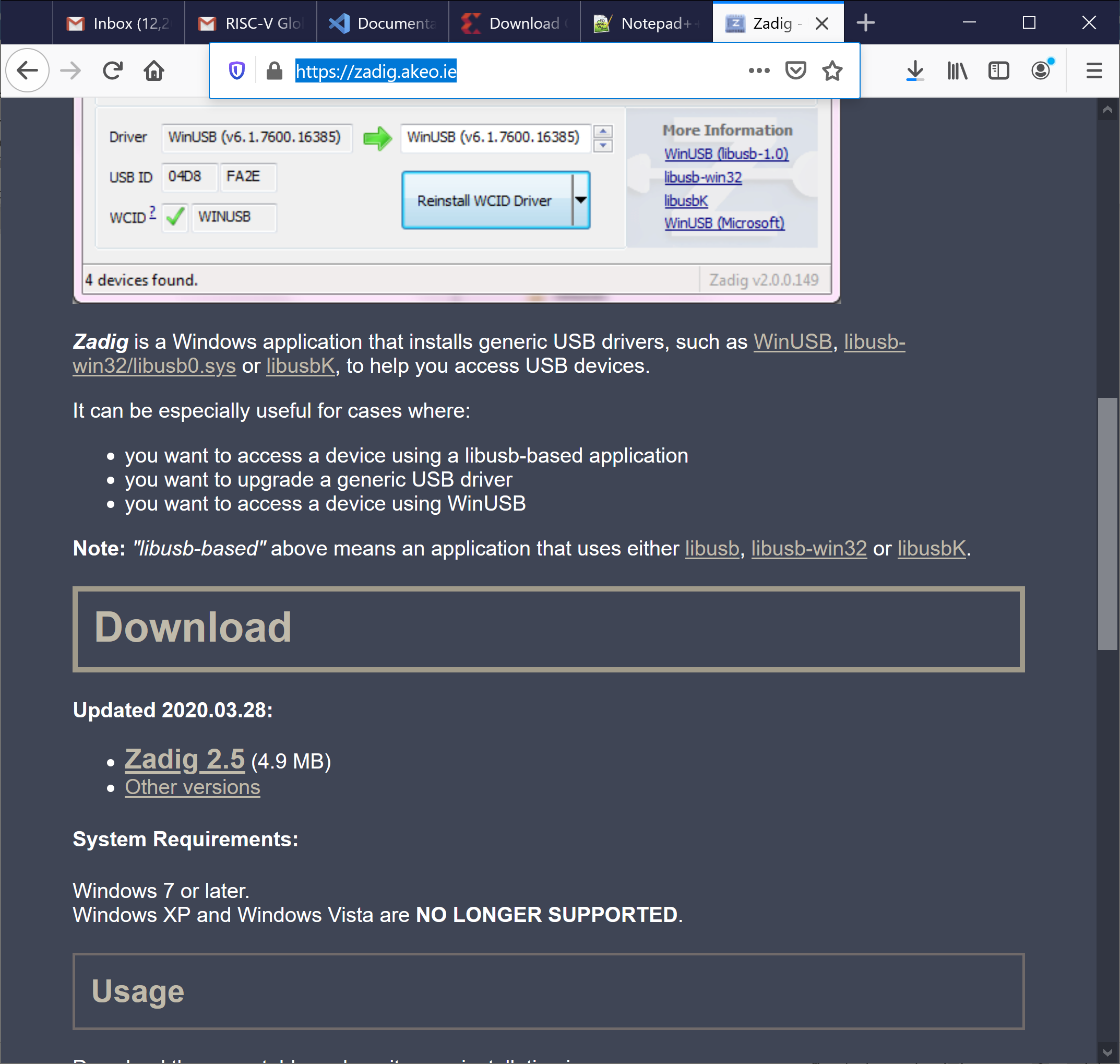
* wget https://github.com/zephyrproject-rtos/sdk-ng/releases/download/v0.12.2/zephyr-sdk-0.12.2-x86\_64-linux-setup.run
* chmod +x zephyr-sdk-0.12.2-x86\_64-linux-setup.run
* ./zephyr-sdk-0.12.2-x86\_64-linux-setup.run -- -d ~/zephyr-sdk-0.12.2

If installing the Zephyr SDK outside any of those locations, please read: [Install the Zephyr Software Development Kit (SDK)](https://docs.zephyrproject.org/latest/getting_started/installation_linux.html#zephyr-sdk). You cannot move the SDK directory after you have installed it.

# Appendix A: Installing drivers in Windows to use PlatformIO

To download the Zadig executable, browse to the following website (see Figure 4):

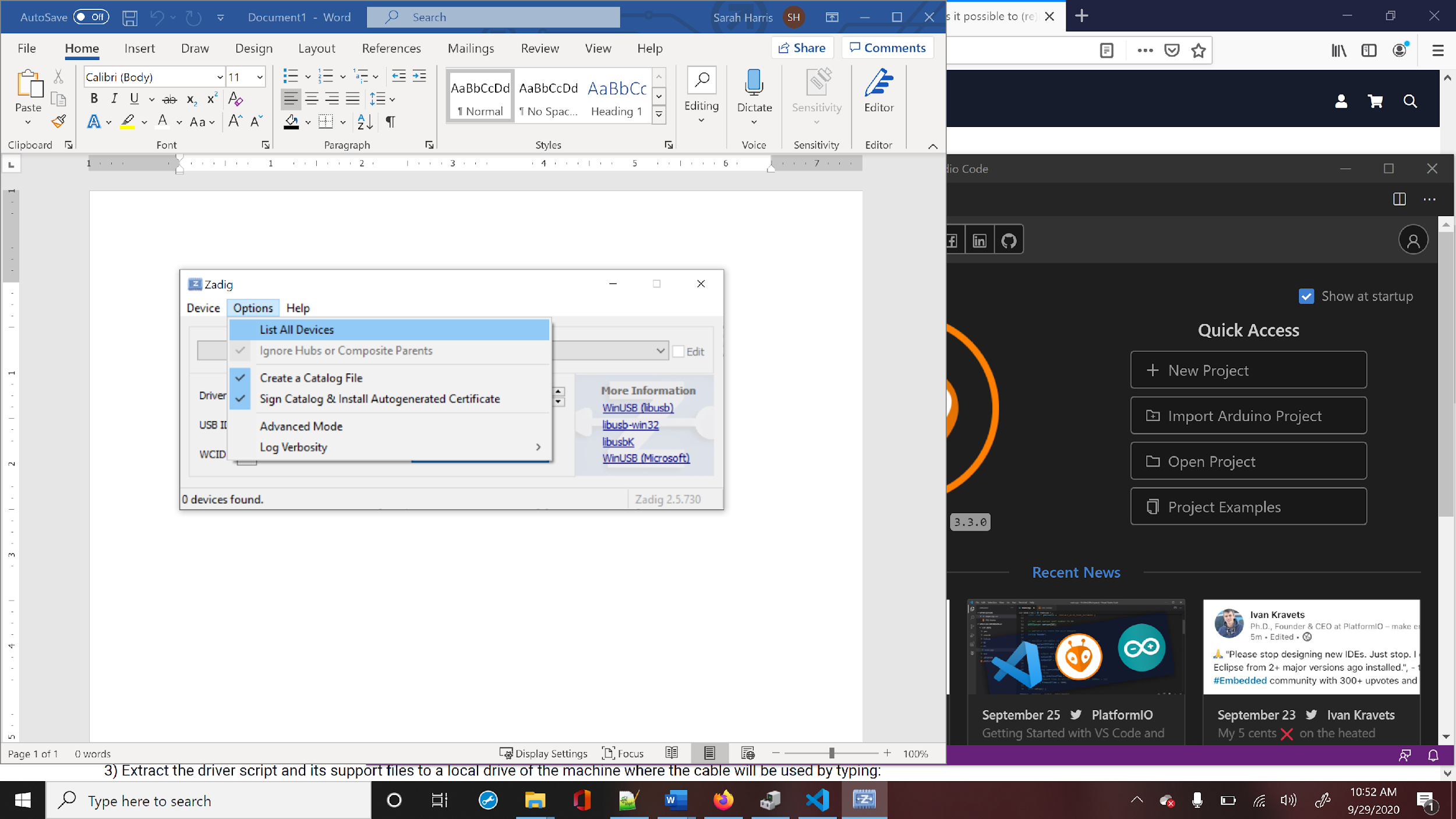
<https://zadig.akeo.ie/>



**Figure 4. Install Nexys A7 board driver used by PlatformIO**

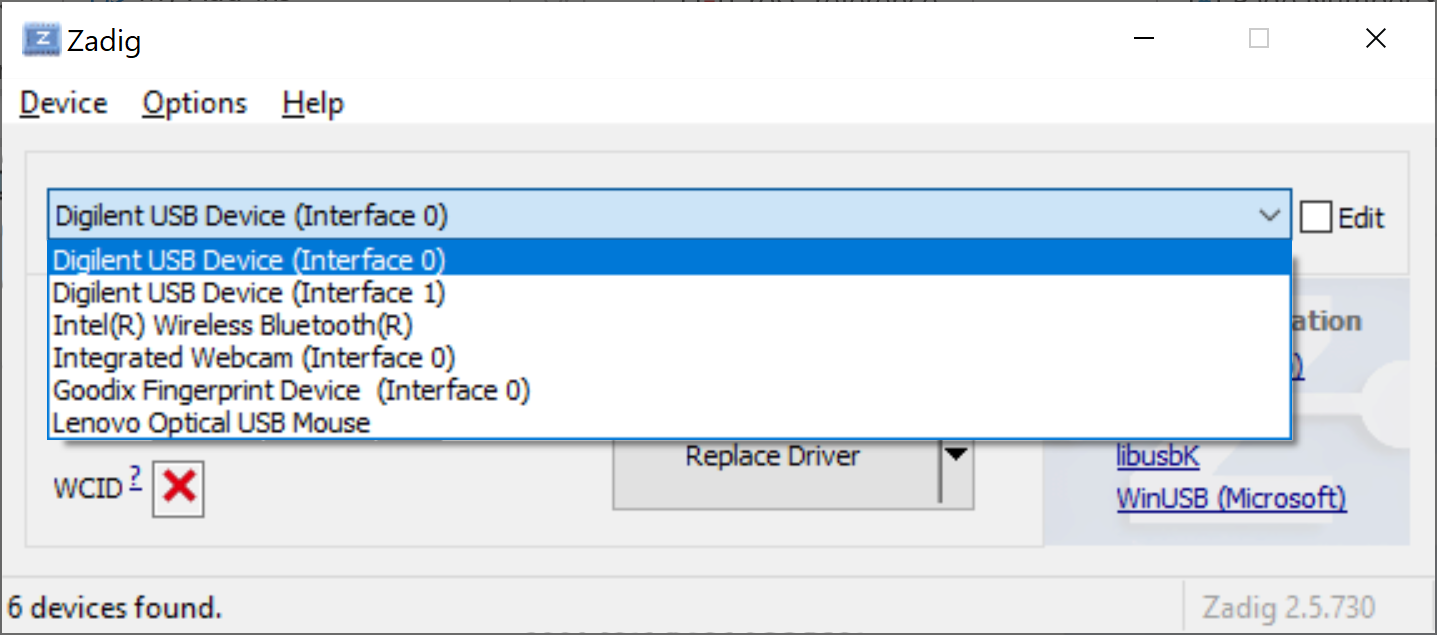
Click on Zadig 2.5 and save the executable. Then run it (zadig-2.5.exe), which is located where you downloaded it. You can also type zadig into the Start menu to find it. You will probably be asked if you want to allow Zadig to make changes to your computer and if you will let it check for updates. Click Yes both times.

Connect the Nexys A7 Board to your computer and switch it on. In Zadig, click on Options → List All Devices (see Figure 5).



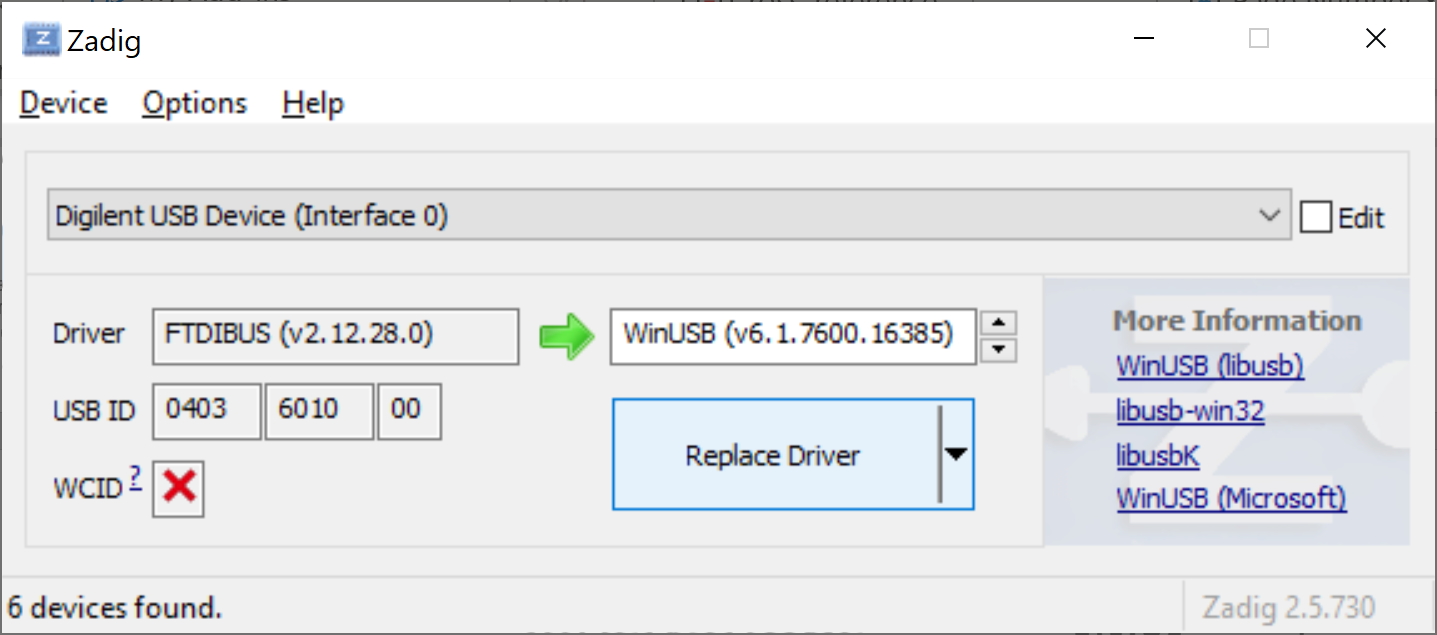
**Figure 5. List all devices in Zadig**

If you click on the drop-down menu, you will see Digilent USB Device (Interface 0) and Digilent USB Device (Interface 1) listed. You will install new drivers for only Digilent USB Device (Interface 0) (see Figure 6).



**Figure 6. Install WinUSB driver for Digilent USB Device (Interface 0)**

You will now replace the FTDI driver with the WinUSB driver, as shown in Figure 7. Click on Replace Driver (or Install Driver) for Digilent USB Device (Interface 0). You are installing the driver for the Nexys A7 board or, if you previously installed Vivado, you are replacing the FTDI driver used by Vivado with the WinUSB driver used by PlatformIO.



**Figure 7. Replace driver for Nexys A7 board**

After some time, typically several minutes, Zadig will indicate the driver was installed correctly. Click Close and then close the Zadig window.

Next time you use PlatformIO you do not need to re-install the driver. However, note that **this driver is not compatible with Vivado in Windows**.

# Appendix B: Installing Verilator and GTKWave in Windows

In this section, we explain how to install Verilator and GTKWave in Windows 10. In Windows, you must use Cygwin to install Verilator, so we first explain how to install this programming/runtime environment.

1. **Cygwin Installation :**

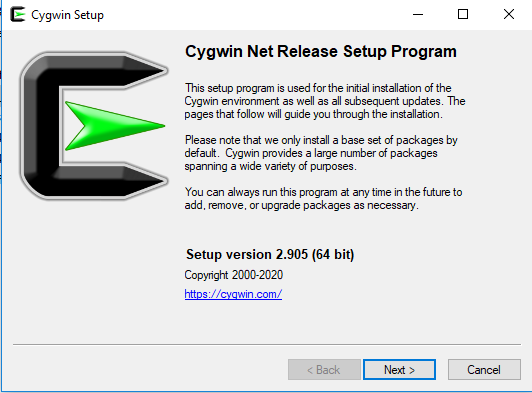
As described on its webpage (<https://www.cygwin.com>), Cygwin consists of GNU and Open Source tools which provide functionality on Windows similar to that of a Linux distribution. Follow the next steps to install Cygwin on Windows 10.

1. Navigate to the installation webpage (<https://cygwin.com/install.html>) and download the installation file, called *setup-x86\_64.exe* (Figure 8).

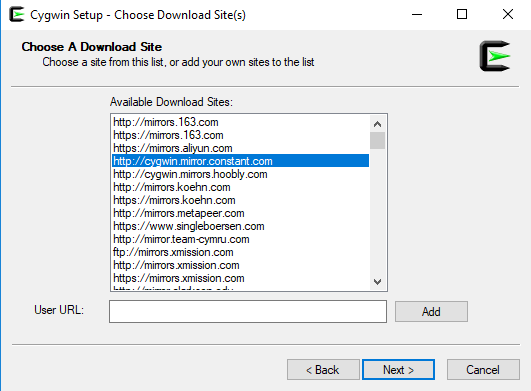


**Figure 8. Cygwin installation webpage**

1. Execute the setup file in your machine by double-clicking on it (Figure 9). Click **Next** several times, maintaining the default options. The installer will ask you to **Choose a Download Site** (Figure 10), you can choose any one of them.

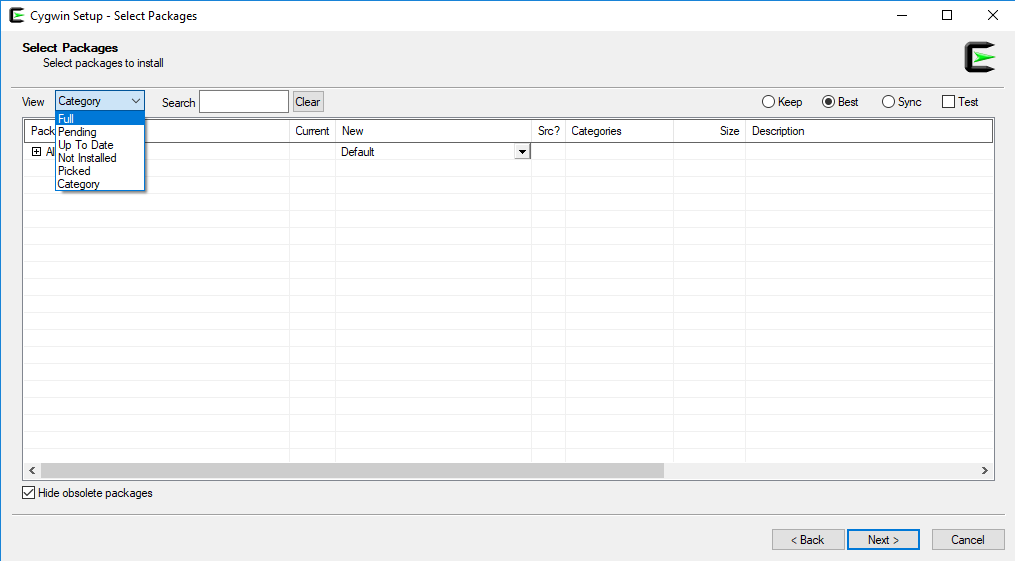


**Figure 9. Cygwin installation window**



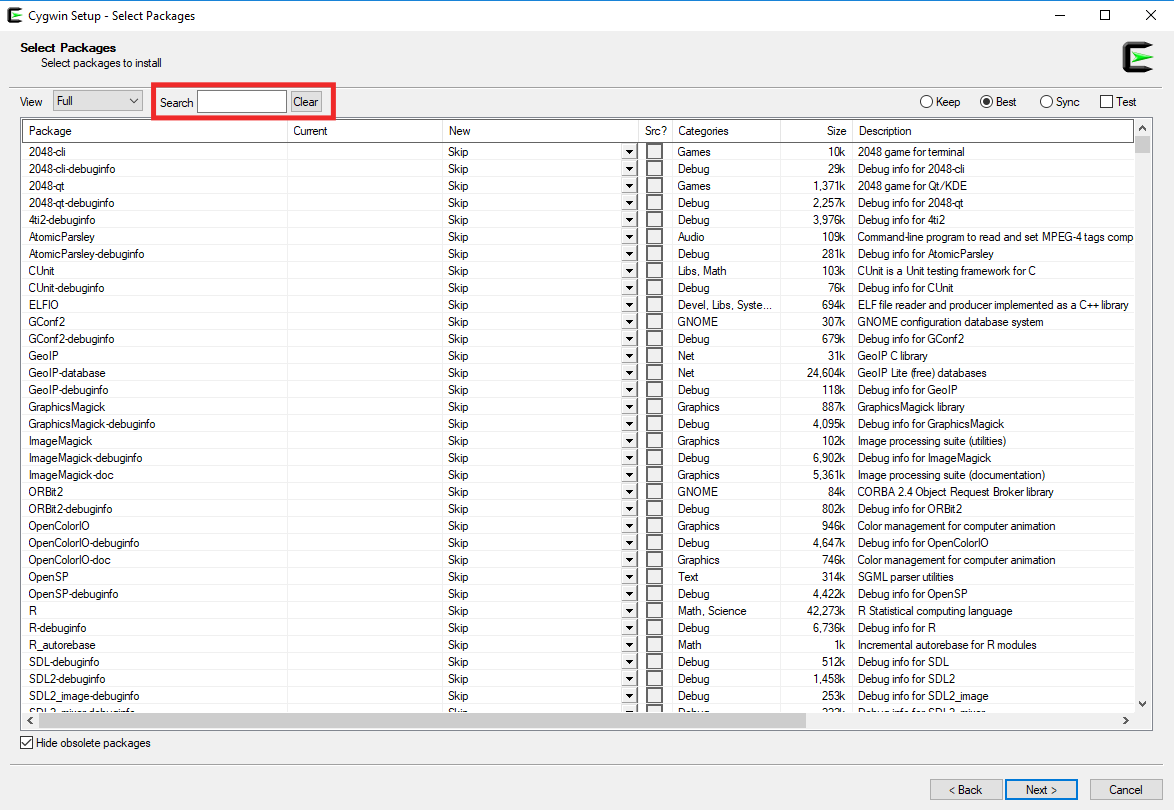
**Figure 10. Choose Download Site**

1. After several steps, you will reach the **Select Packages** window (Figure 11). Select the **Full** view, as shown in Figure 11.



**Figure 11. Select Packages window**

1. The complete list of packages that you can install will appear (Figure 12). In the **Search** box, select the specific packages that you want to install.



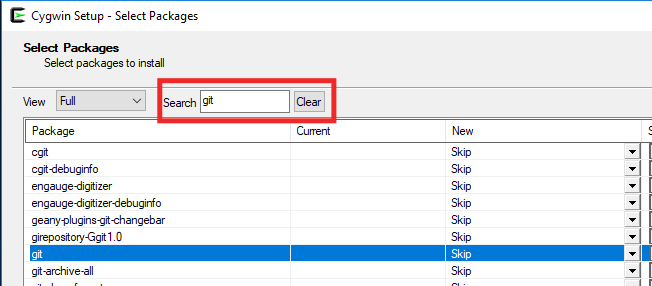
**Figure 12. Select Packages window – Full view**

To be able to compile Verilator and generate a new simulator binary, you need to install the following packages:

* git
* make
* autoconf
* gcc-core
* gcc-g++
* flex
* bison
* perl
* libargp-devel

Include at least these packages in your Cygwin installation. Select them one-by-one following the steps below (we only show the detailed steps for the first package in the list, git; the process is the same for the other packages):

* Look for the git package in the **Search** box (Figure 13).



**Figure 13. Look for the git package**

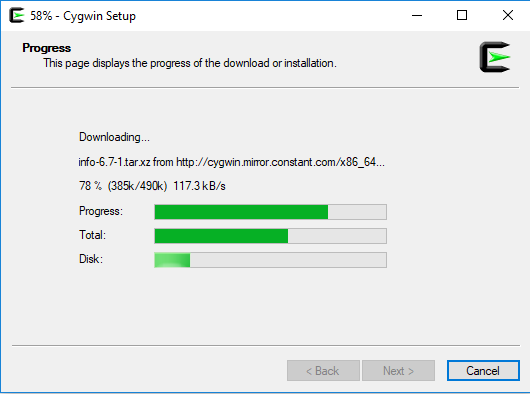
* Select the most up-to-date version in the dropdown menu **and** tick the box (Figure 14).



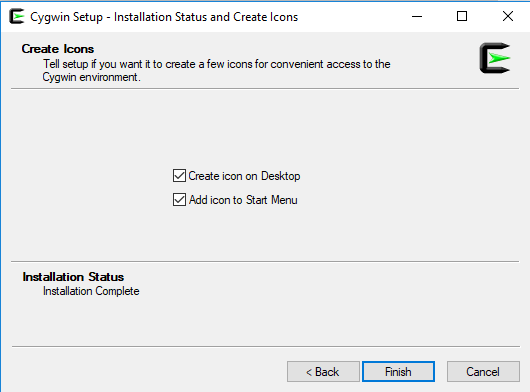
**Figure 14. Select the most up-to-date version and tick the box**

* Do the same for the remaining packages in the above list.

1. Once you have selected the nine packages, click **Next** in the subsequent windows to include these packages in your Cygwin installation (the installation process, see Figure 15, may take several minutes) and finalize the installation by clicking Finish (Figure 16).



**Figure 15. Cygwin setup**

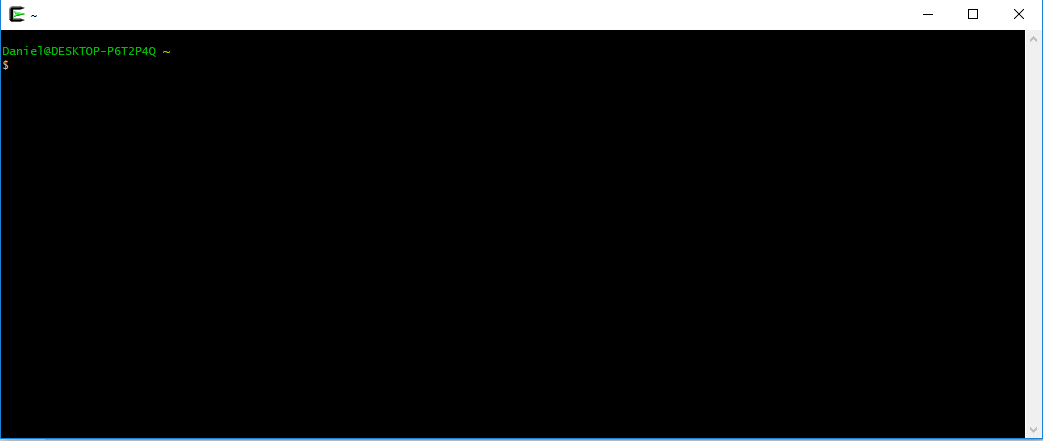


**Figure 16. Finish the installation**

1. If you need to add a package to your Cygwin installation, repeat steps 2-5 for that package.
2. **Verilator Installation in Windows:**

Follow the next steps to install Verilator on Windows 10.

1. Open the Cygwin terminal (Figure 17), available on your Windows Desktop or from the Start menu.



**Figure 17. Cygwin terminal**

1. Build and install Verilator by following these steps. This may take some time (even hours), depending on the speed of your computer:

* git clone https://git.veripool.org/git/verilator
* cd verilator
* git pull
* git checkout v4.020
* autoconf
* ./configure
* make
* make install

1. **GTKWave Installation in Windows:**

GTKWave can be downloaded as a precompiled package from <https://sourceforge.net/projects/gtkwave/files/>. Look for the most recent Windows package (at the time this document was written, it was called ***gtkwave-3.3.100-bin-win64***), and download and unzip (uncompress) it. You can find an executable file called *gtkwave* inside folder *bin*, which you can execute and use in your Windows machine.